

# LaTeX Tutorial

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DiGS, 2009

# Outline

## 1 Introduction

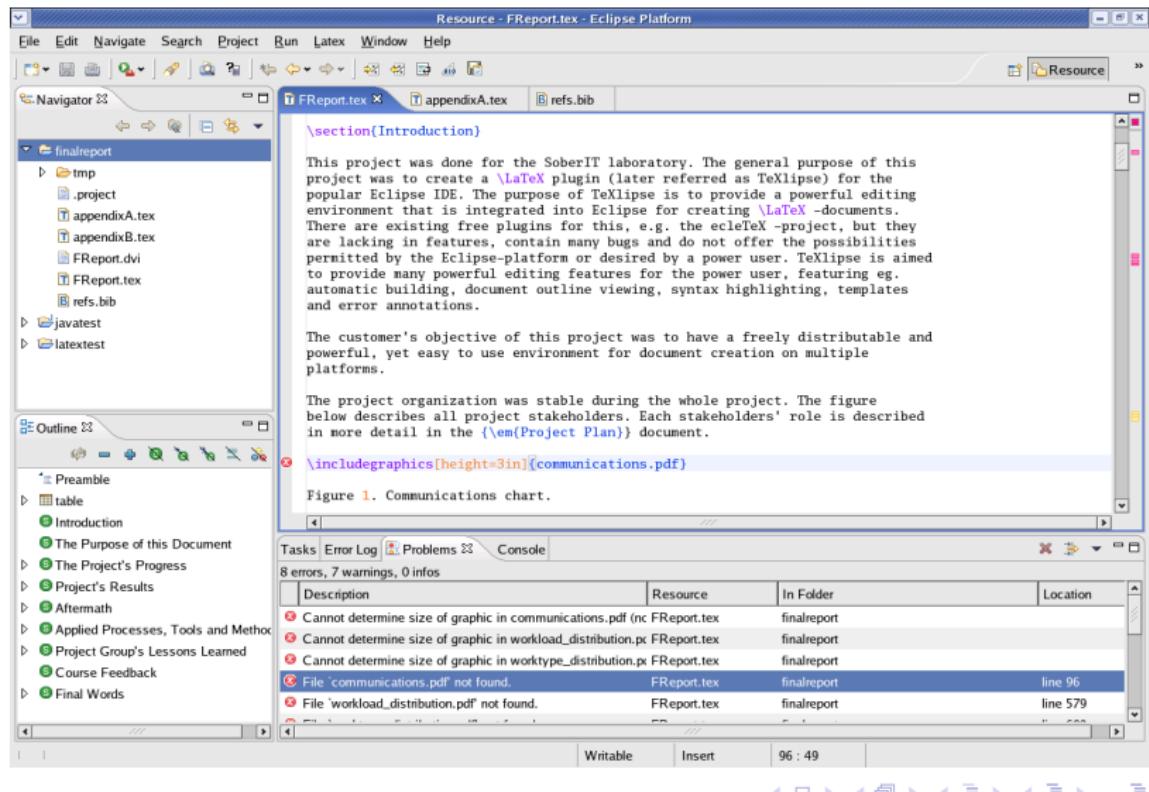
- Eclipse LaTeX Plugins
- CVS and Eclipse

## 2 LaTeX Document

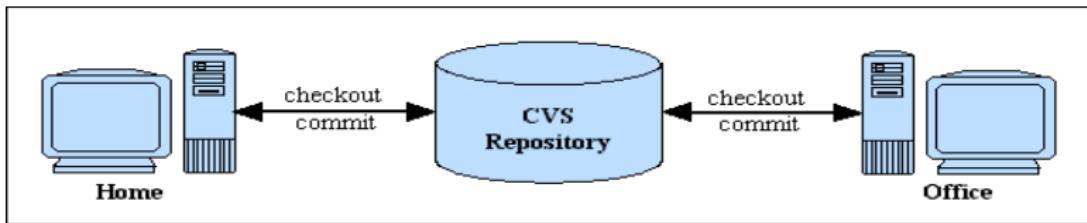
- Document Layout
- Document Formatting

## 3 Resources

# TeXlipse: <http://texlipse.sourceforge.net/>



# Configuration Management with CVS



## Setup

- ① Set CVSROOT environment variable

```
CVSROOT=/csd/thesis/rbahati/DiGS  
export CVSROOT
```

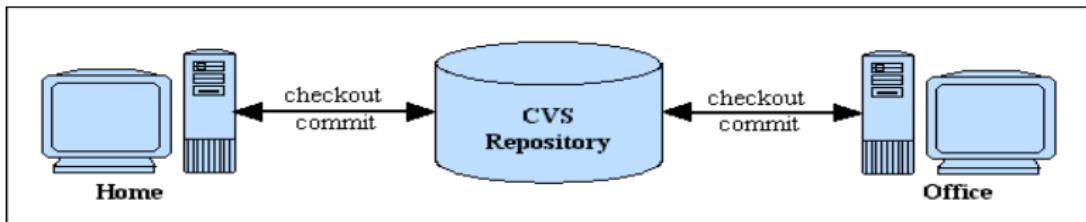
- ② Create repository

```
cvs init
```

- ③ Initialize the project

```
cvs import -m "LaTeX" LaTeX-2009 rbahati start
```

# Configuration Management with CVS



## Setup

- ① Set CVSROOT environment variable

```
CVSROOT=/csd/thesis/rbahati/DiGS  
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```

# Small Document

```
\documentclass[journal]{IEEEtran}
\usepackage{algorithm}
\usepackage{algorithmic}
\usepackage{listings}
\usepackage{epsfig}

\begin{document}
\title{Document Tittle}
\author{Document Author}
\maketitle

\section{First Section}
\subsection{First Subsection}
\subsubsection{First Subsubsection}
\subsubsection{Second Subsubsection}

\section{Second Section}
\subsection{Second First Subsection}
\subsection{Second Second Subsection}

\bibliographystyle{IEEEtran}
\bibliography{bib-file}
\end{document}
```

# Large Document

```
\documentclass[11pt, leqno]{report}
\usepackage{amsmath, amssymb, amsfonts}
\usepackage{listings}
\usepackage{epsfig}

\begin{document}
\title{Document Title}
\author{Document Author}
\maketitle

\pagestyle{plain}
\addcontentsline{toc}{chapter}{Contents}
\pagenumbering{roman}
\tableofcontents

\include{ch-introduction}
\include{ch-modelling-RL}

\bibliographystyle{IEEEtran}
\bibliography{raphael-PhDDISSERTATION}
\appendix
\include{appendix-policies}
\include{appendix-cycle}
\end{document}
```

# Chapter: ch-modelling-RL

```
\chapter{Modelling Reinforcement Learning}
\label{ch:modelling-RL}

\section{State-Transition Model}
\label{sec:state-transition-model}
\subsection{System States}
\label{sec:system-states}
\subsection{System Transitions}
\label{sec:system-transitions}
\section{Reward Function}
\label{sec:reward-function}

\section{Exploration/Exploitation}
\label{sec:exploration-exploitation}
\subsection{Exploration Strategy}
\label{sec:exploration-strategy}
\subsection{Exploitation Strategy}
\label{sec:exploitation-strategy}

\section{Learning by Reinforcement}
\label{sec:learning-by-reinforcement}

\section{Discussion}
\label{sec:modelling-RL-discussion}
```

# Document Classes and Packages

## documentstyle[options]{class}

- ① **{article}**: 11pt, 12pt, twoside, twocolumn, draft, fleqn, leqno, acm
- ② **{report}**: 11pt, 12pt, twoside, twocolumn, draft, fleqn, leqno, acm
- ③ **{letter}**: 11pt, 12pt, fleqn, leqno, acm
- ④ **{book}**: 11pt, 12pt, twoside, twocolumn, draft, fleqn, leqno

## usepackage{package}

- **{amsmath,amssymb,amsfonts}**: Mathematics
- **{epsfig}**: Figures (.jpeg, .png)
- **{subfigure}**: SubFigures
- **{listings}**: Codes
- **{algorithm, algorithmic}**: Algorithms
- **{multirow}**: Table formatting

# Bibliography

@INPROCEEDINGS; @TECHREPORT; @ELECTRONIC; @INBOOK;  
@PHDTHESIS; @MASTERSTHESIS;

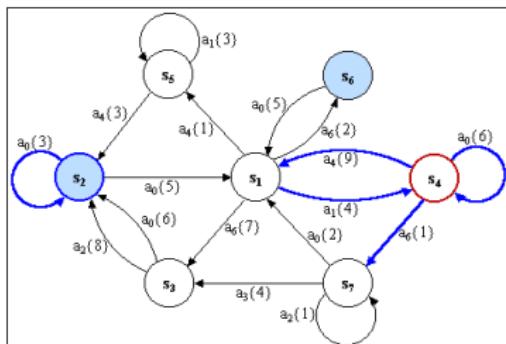
```
@INPROCEEDINGS{REF502,  
    TITLE = "{Reinforcement Learning in Policy-driven Autonomic  
              Management}" ,  
    YEAR = "2008" ,  
    PAGES = "899--902" ,  
    MONTH = "April" ,  
    BOOKTITLE = "Network Operations \& Management Symposium  
                (NOMS'08)" ,  
    ADDRESS = "Salvador, Bahia, Brazil" ,  
    FILE = "raphael-NOMS2008.pdf" ,  
    AUTHOR = "Raphael M. Bahati and Michael A. Bauer"  
}
```

## Reference

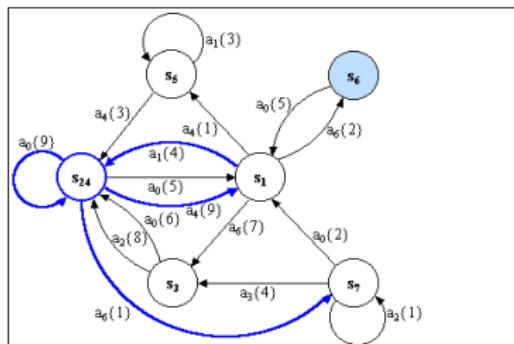
- ① R. M. Bahati and M. A. Bauer, “Reinforcement Learning in Policy-driven Autonomic Management,” in *Network Operations & Management Symposium (NOMS’08)*, Salvador, Bahia, Brazil, April 2008, pp. 899–902.

Figures: `\usepackage{epsfig, subfigure}`

```
\begin{figure}[htb]
\begin{center}
\subfigure[Original model]{\label{fig:change7}
\epsfig{file=figures/change7, height=1.3in, width=1.9in}}
\epsfig{file=figures/arrow3, height=1.3in, width=0.2in}
\subfigure[New model]{\label{fig:modification7}
\epsfig{file=figures/modification7, height=1.3in, width=1.9in}}
\caption{Sample Table.}
\end{center}
\end{figure}
```



(a) Original model



(b) New model

Figure: Sample Figure.

# Tables: `\usepackage{multirow}`

```
\begin{table}[htb]
\begin{center}
\begin{small}
\begin{tabular}{|c|c|c|c|p{2.2 in}|}
\hline
State & $R_{m_j}^k \& f(R_{m_j}^k) \& \multicolumn{2}{c|}{{\$A_{s_i}}}$ \\
\hline
\$s_i \& \$R_{m_1}^k \& f(R_{m_1}^k) \& a_1 \& State\_action \\
\hline
\multirow{4}{*}{\$s_1} \& \multirow{4}{*}{$R_{m_1}^3$} \& \multirow{4}{*}{$f(R_{m_1}^3)$} \& \gamma - action \\
& \multirow{4}{*}{0} \& \texttt{\$gamma-action} \\
\cline{4-5} \& \& a_1 \& \texttt{AdjustMaxClients(+25)} \\
\cline{4-5} \& \& a_2 \& \texttt{AdjustMaxKARespects(-30)} \\
\cline{4-5} \& \& a_3 \& \texttt{AdjustMaxBandwidth(-128)} \\
\hline
\end{tabular}
\end{small}
\end{center}
\caption{Sample Table.}
\label{tab:system-states}
\end{table}
```

# Tables

State	$R_{m_j}^k$	$f(R_{m_j}^k)$	$A(s_i)$	
$s_i$	$R_{m_1}^k$	$f(R_{m_1}^k)$	$a_l$	State action
$s_1$	$R_{m_1}^3$	0	$a_0$	$\gamma$ -action
			$a_1$	AdjustMaxClients(+25)
			$a_2$	AdjustMaxKAResquests(-30)
			$a_3$	AdjustMaxBandwidth(-128)

Table: Sample Table.

# Equations

```
\begin{equation}
Q_0(s,a)=\frac{\sum\limits_{p_j \in [P_v]_a} \tanh[S(p_j)] \times W_a(p_j)}{\tanh[S(p_j)] \times W_a(p_j) \| [P_v]_a \|} \\
\label{eq:action-strength}
\end{equation}
```

## Equation

$$Q_0(s, a) = \frac{\sum_{p_j \in [P_v]_a} \tanh[S(p_j)] \times W_a(p_j)}{\| [P_v]_a \|} \quad (1)$$

# Equations

```
\begin{align}
S(p_1) &= \sum\limits_{c_i \in p_1} c_i \cdot \omega \\
&\quad \times V(c_i) \\
&= \{\frac{1}{6} \times 0.0588\} + \{\frac{1}{6} \times 1.0000\} \\
&= 0.0098 + 0.1667 \\
&= 0.1765
\end{align}
```

## Equation

$$S(p_1) = \sum_{c_i \in p_1} c_i \cdot \omega \times V(c_i) \tag{2}$$

$$= \left\{ \frac{1}{6} \times 0.0588 \right\} + \left\{ \frac{1}{6} \times 1.0000 \right\} \tag{3}$$

$$= 0.0098 + 0.1667 \tag{4}$$

$$= 0.1765 \tag{5}$$

# Listings: `\usepackage{listings}`

```
\begin{figure}[htb]
\begin{center}
\lstset{language=C++, numbers=left , basicstyle=\tiny}
\lstinputlisting{listings/listing.cpp}
\label{lis:listing-cpp}
\end{center}
\end{figure}
```

```
1 status_t ActionTestList::getValidActionTest( ActionTestInfo **entry )
2 {
3     register int count;
4     if (lock() == NOTOK)
5         return NOTOK;
6     for (count = 0; count < numItems; count++)
7     {
8         if ( actionList [ count ].type != INVALID_TEST )
9         {
10             *entry = &actionList [ count ];
11             break;
12         }
13     }
14     if (unlock() == NOTOK)
15         return NOTOK;
16     return OK;
17 }
```

# Algorithms: usepackage{algorithm, algorithmic}

```
\begin{algorithm}
\caption{\texttt{CreateState}($E_{-m}', A_{-v}$)}
\label{pro:create-state}
\begin{algorithmic}[1]
\REQUIRE $r_{-m_{-i}} \in M_{-R}^{P}$
\ENSURE $s = \langle \mu, M(s), A(s) \rangle$ 
\FOR {each $e \in E_{-m}'} {
    \FOR {each $r_{-m_{-i}} \in M_{-R}^{P}$} {
        \IF {$(\alpha_{-m_{-i}}, \text{metric}) = e, (\text{metric})$} {
            STATE $s.m_{-i} \leftarrow \text{ID} \leftarrow \alpha_{-m_{-i}} \leftarrow \text{ID}$
            STATE $s.m_{-i} \leftarrow \omega \leftarrow \alpha_{-m_{-i}} \leftarrow \omega$
            STATE $s.m_{-i} \leftarrow \text{value} \leftarrow e \leftarrow \text{value}$
            STATE $s.m_{-i}.f(R_{-m_{-i}})^{l_i} \leftarrow \text{Region}(\text{value}, \sigma_{-m_{-i}})$
            STATE $M(s) \leftarrow M(s) \cup s.m_{-i}$
            STATE break;
        \ENDIF \label{line-C:create-state}
    \ENDFOR
}
\ENDFOR
STATE $M(s) \leftarrow \text{Sort}(M(s), s.m_{-i}) \leftarrow \text{ID}$
STATE $a_{-0} \leftarrow \text{$\gamma$-action} \leftarrow \text{A}(s) \cup a_{-0}$
\FOR {each $a_{-i} \in A_{-v}$} {
    STATE $A(s) \leftarrow A(s) \cup a_{-i}$
}
\ENDFOR
RETURN $s$
\end{algorithmic}
\end{algorithm}
```

---

## Algorithm 1 CreateState( $E'_m, A_v$ )

---

**Input:**  $r_{m_i} \in M_R^P$

**Output:**  $s = \langle \mu, M(s), A(s) \rangle$

```
1: for each  $e \in E'_m$  do
2:   for each  $r_{m_i} \in M_R^P$  do
3:     if ( $\alpha_{m_i}.\text{metric} = e.\text{metric}$ ) then
4:        $s.m_i.\text{ID} \leftarrow \alpha_{m_i}.\text{ID}$ 
5:        $s.m_i.\omega \leftarrow \alpha_{m_i}.\omega$ 
6:        $s.m_i.\text{value} \leftarrow e.\text{value}$ 
7:        $s.m_i.f(R_{m_i}^l) \leftarrow \text{ComputeRegionValue}(e.\text{value}, \sigma_{m_i})$ 
8:        $M(s) \leftarrow M(s) \cup s.m_i$ 
9:       break;
10:      end if
11:    end for
12:  end for
13:   $M(s) \leftarrow \text{Sort}(M(s), s.m_i.\text{ID})$ 
14:   $a_0 \leftarrow \gamma\text{-action}$ 
15:   $A(s) \leftarrow A(s) \cup a_0$ 
16:  for each  $a_i \in A_v$  do
17:     $A(s) \leftarrow A(s) \cup a_i$ 
18:  end for
19: return  $s$ 
```

---

# Resources

- ① **CVS**: <http://www.cs.d.uwo.ca/~rbahati/courses/CS212b/resources.html>
- ② **LaTeX**: <http://frodo.elon.edu/tutorial/tutorial/node1.html>
- ③ **TeXlipse**: <http://texlipse.sourceforge.net/>
- ④ **Beamer**: <http://latex-beamer.sourceforge.net/>